
Contents

1. Introduction	9
2. Basic concepts	13
2.1. Definitions of robots	14
2.2. Special uses of robots	15
2.3. Industrial robotics and automation	20
2.4. Classification of industrial robots	21
2.5. Constructions of industrial robots	25
2.6. Technical parameters of industrial robots	41
2.7. Selected constructions of industrial robots	58
2.7.1. Five- and six-axis articulated robots	59
2.7.2. Parallel robots	63
2.7.3. SCARA robots	68
2.7.4. Portal robots	70
2.7.5. Two-arm robots	71
2.7.6. Collaborative robots	77
2.8. Coordinate systems of industrial robots	82
3. Effectors of industrial robots	88
3.1. Grippers	88
3.2. Robotic tools	99
3.3. Tools change systems	100

4. Sensors and sensory systems of industrial robots	103
4.1. Measurement sensors	103
4.2. Vision systems	120
5. The use of industrial robots in selected applications	134
5.1. The advantages of robotization	135
5.2. Robotic welding stations	136
5.3. Packaging machines vs. robots	140
5.4. New markets for robotics	142
5.5. Work in dangerous conditions	142
5.6. Constant development of robotics	145
6. Analysis of robotic sorting, packaging and palletizing processes	147
6.1. Designing robotic positions for sorting, packing and palletizing of goods	149
6.2. Structure of robotic sorting, packaging and palletizing workstations	150
6.2.1. Robotic sorting of goods	152
6.2.2. Robotic packaging of goods	154
6.2.3. Robotic palletizing of goods	156
6.3. Safety and work environment at sorting, packaging and palletizing workstations	161
6.4. Examples of robotic packaging and palletizing stations	164
7. Robotic processes of welding and laser welding and cutting	170
7.1. Robotic processes of arc welding	171
7.2. Robotic processes of spot welding	182
7.3. Examples of robotic spot welding stations	194
7.4. Robotic processes of laser welding and cutting	198
7.5. Summary	209
8. Robotic machine tending	210
8.1. Robotic tending of machining centers	210
8.2. Robotic tending of plastic forming stations	215

9. Robotic assembly	220
9.1. Types of assembly stations	224
9.2. Summary	229
10. Programmable Logic Controllers (PLCs) in robotic production cells	231
10.1. Position of PLCs in industry	232
10.2. Construction, operation and programming of PLCs	232
10.3. Immigration of drivers to robot controllers	235
10.3.1. Examples of solutions	236
10.4. Summary	245
11. Safety systems at robotic work stations	246
11.1. Machine safety in the aspect of standards requirements	247
11.2. Categories of safety	249
11.3. Safety in a robotic production cell	255
11.4. Safety systems vs. control systems of industrial robots	259
11.5. Summary	265
12. The market of robotics, review of new solutions and trends	266
12.1. The density of robotization	269
12.2. Predictions on the development of robotization	270
12.3. The main factors influencing the development of robotization	270
12.4. Trends in the development of industrial robots	272
12.4.1. Construction of manipulators	272
12.4.2. Generations of controllers	276
12.4.3. Development of operator panels – Teach Pendant panels	279
12.4.4. Development of safety systems of industrial robots	281
12.4.5. Development of the environments for programming industrial robots	283
12.4.6. Integrated systems for quick implementation	286
13. References	288